

OFEG-Tech meeting, Kiel 1-2nd December 2010 Holland I ROV Operations

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"Holland 1" ROV General.

- •Scientific version of the "Quasar" ROV system. 3000m Rated
- •Consists of ROV,TMS, LARS, Winch, Control van, Workshop and deck equipment.
- Delivered in September 2008
- 2 full survey seasons completed
- •(6 surveys, I Trial)
- •2009: 26 Scientific dives: 101 hours
- •2010 51 scientific dives: 205 hours
- •3 dives to full depth (3000m)
- Majority of operations 750-2000m





Personnel

- 2009 operations largely completed with contract personnel (eventful year)
- 2010 full time manager/chief pilot engaged, 2nd full time pilot/technician recruited. Contractors used for rest of team
- Manning: min 3 for 12 hour operations, 6 personnel minimum for 24 hour operations
- Heavy workload for maintenance and operations given small team



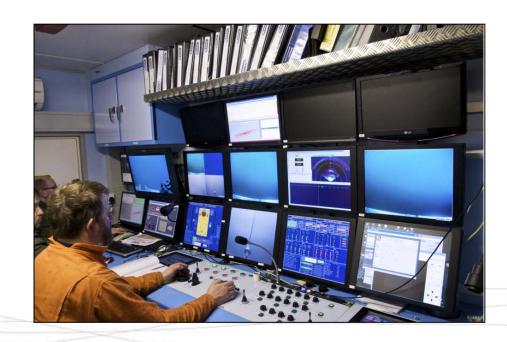
2011

- 2 surveys planned for 2011
- C. 50 operational days (summer)
- Mobilisation c. 2..5 days, demobilisation c. I day (.5!)
- System free from August April typically



ROV.

- •Up-rated version of the Quasar ROV system. Ist Quasar to built by SMD.
- •ROV Weight 3.3 Tonnes
- Up to 250kg of payload on the ROV
- Capacity to add additional tooling skids
- Maximum air weight of vehicle up to 6000kg.
- Hydraulic ROV 100hp





Hydraulic Power.

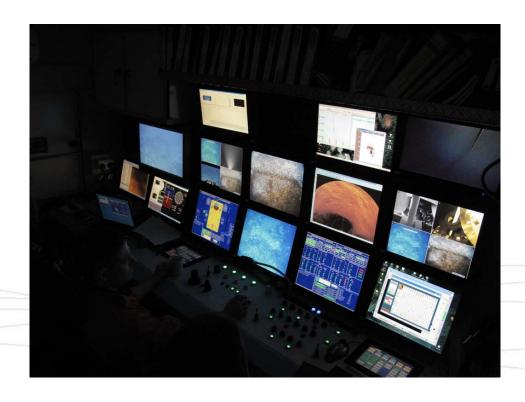
- 3000v 75kw 4 pole motor driving the hydraulic pump.
- Hydraulic pump produces up to 250 bar.
- Four lateral and three vertical thrusters Two intelligent 12 way valve packs.
- 15 litres per minute flow rate.
- Flow can be controlled on individual functions.
- One high flow function up to 40 litres per minute
- Issues: Oil leaks, Oil contamination, handling oil (lots)





Video Capability.

- I Dedicated high definition video channel using Kongsberg HDTV
- · I Stills camera
- •7 video channels.
- •DVD for standard definition video
- •HDTV Currently recorded to Sony HD tapes.
- Issues: Time coding, copying, data analysis issues
- •Fitting out with capability to record direct to Hard disk in PRORES 422 format to allow simple copying, back up,archival of data





Lighting.

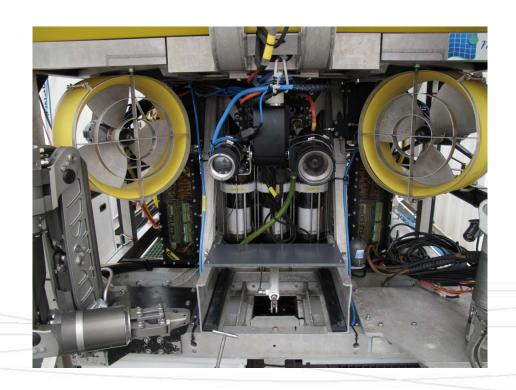
- Two HMI 12000 lumen lights currently fitted.
- Up to 12 dimmable Halogen lights
- Currently making the transition to LED lighting working in conjunction with Cathx Ocean for a complete lighting solution.
- HMI's expensive, LED c. 30% of cost of HMI's
- LED's sensitive to voltage fluctuations





Sensors and Standard equipment.

- · OA SONAR,
- DVL (Station hold),
- Altimeter,
- Digiquartz depth sensor
- Two manipulators.
- Either two seven function or one seven function and one five function.





Spare capacity for additional sensors.

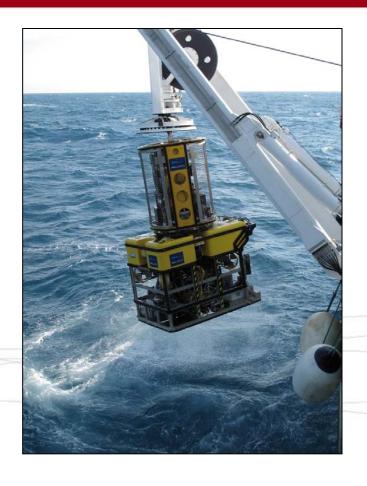
- I Ethernet instrument channel for Seabat/multibeam
- 3 Spare RS232 Channels
- 6 spare switchable RS232/485 Channels.
- 7 analogue channels.
- System set up for Reson 7160 (Trialed April 2010)
- Science skid containing sample boxes and suction sampler
- Integrated Seabird CTD allows integration with wide variety of instruments





TMS.

- Capable of carrying around 400m of tether.
- Power pack 3000v I I.5 hp
- Three cameras.
- Two lights
- Weight in air 2500kg
- Lift termination capacity I 2000kg
- Issues: Docking in marginal conditions and risk of damage to Tether





Free-flying operations

- •Deployment with cable floats trialled in 2010
- •25 x flotation technologies floats utilised
- •Successful deployment using float attachment platform requires additional crew
- Method available in case of TMS issues or specific requirement





Shallow Water Mode/other vessels

- System operated using soft tether only (400m)
- Lock Latch and 20t crane
- Ideal for shallow (sheltered) waters
- System's own 450kva gennerator for power
- Mobilised in 6 hours!





Winch/A Frame

- Winch capable of holding 3250m
 of 31.5mm aroured umbilical
- Portable hydraulically powered A frame (19000kgs)
- Remote operation from ROV shack.
- Winch Fully loaded weighs 24000kg.
- 75kw motor.
- Operates well even in shallow water (no cable heating issues to date





Lessons Learnt/Issues after 2 years operations

- Operating a Full sized work class ROV system from a smaller than normal vessel with a small team .
- Personnel training and retaining regular crew members.
- Tailoring procedures for specific scientific requirements.
- Handling of Data from the HDTV camera system with timecode.
- Developing timelines and communications lines between various groups involved in surveys.